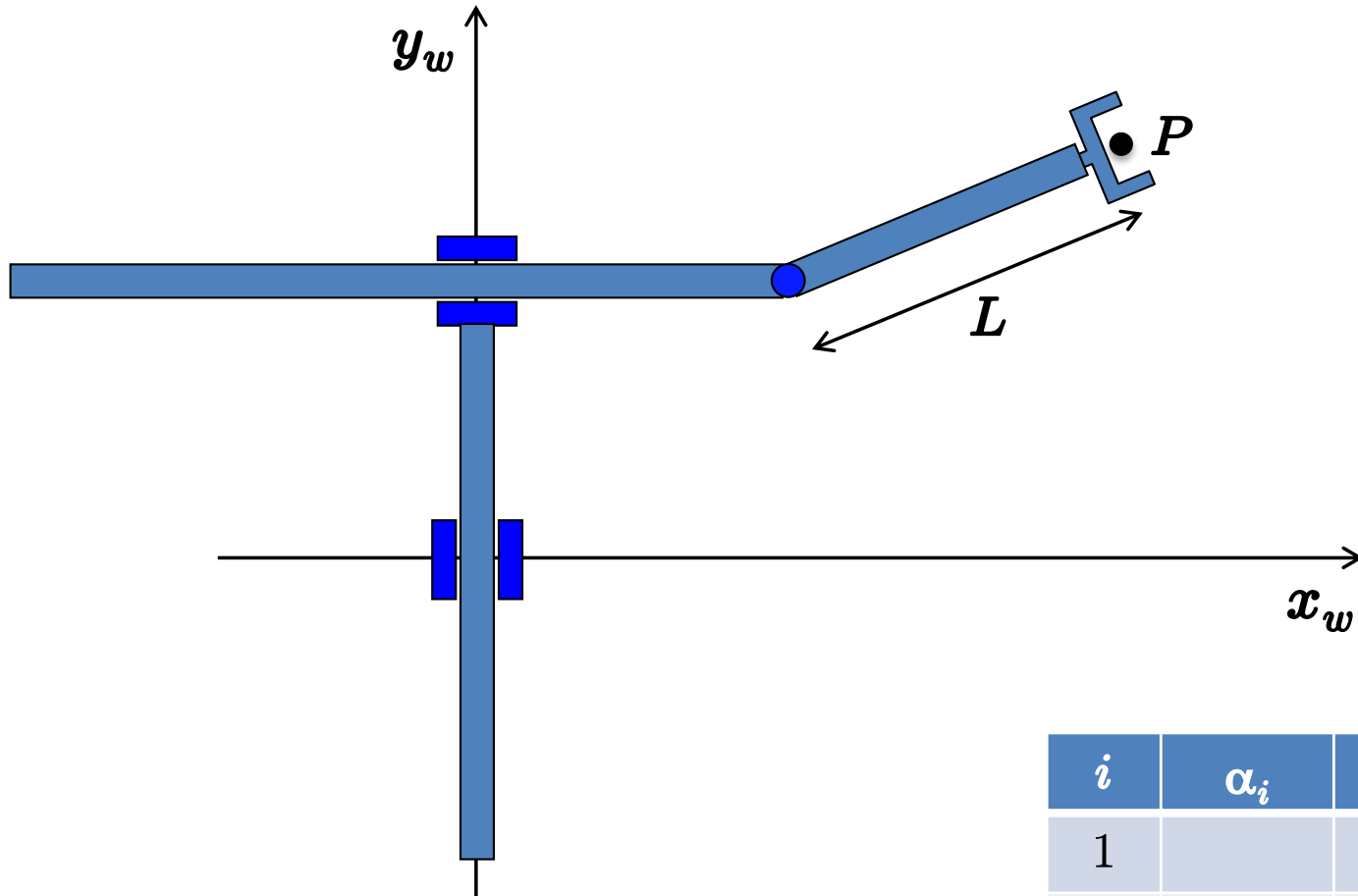


# DH frames assignment and table for a PPR planar robot

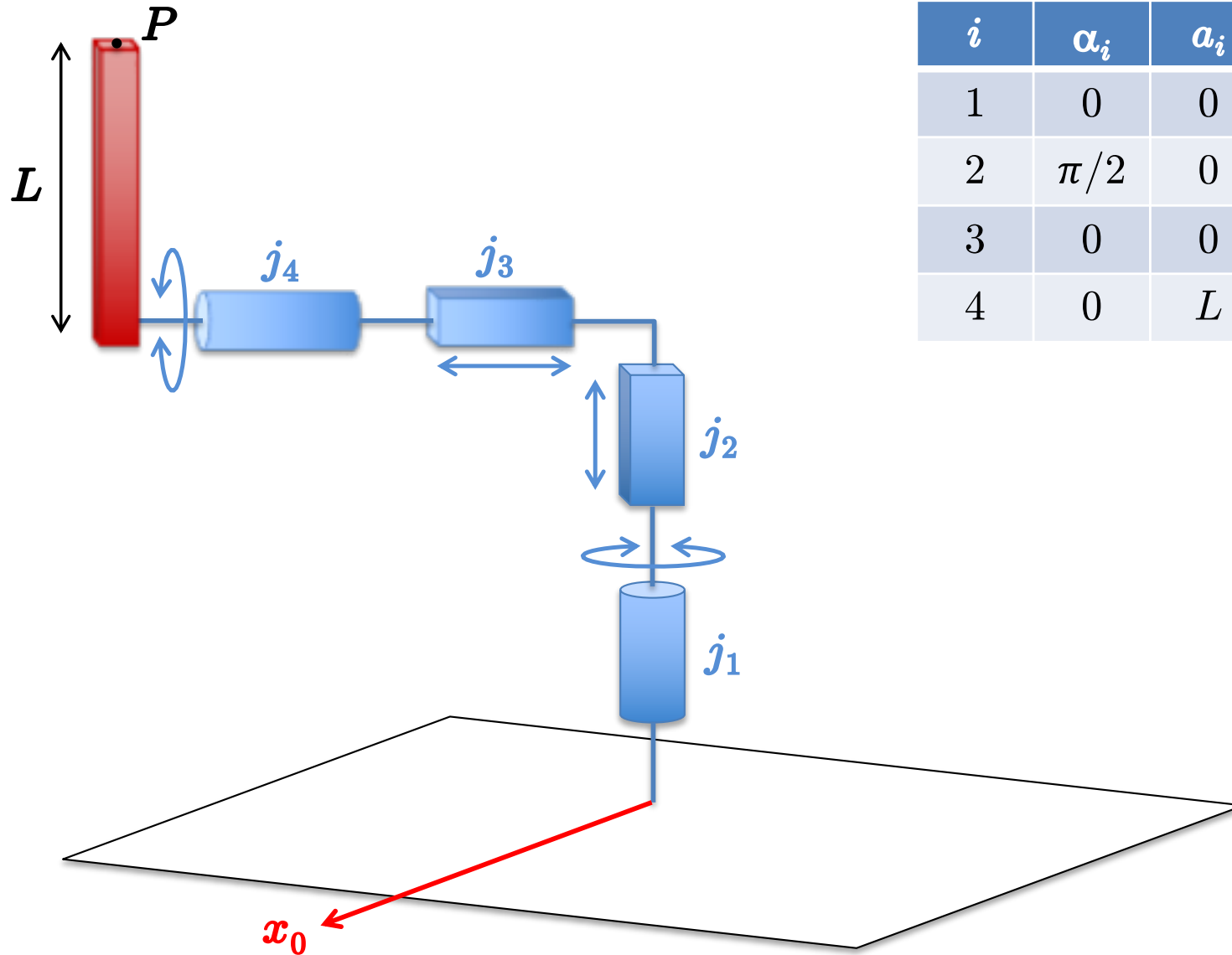
Name: \_\_\_\_\_



$i$	$\alpha_i$	$a_i$	$d_i$	$\theta_i$
1				
2				
3				

# DH frames assignment from the DH table for a RPPR planar robot

Name: \_\_\_\_\_



$i$	$\alpha_i$	$a_i$	$d_i$	$\theta_i$
1	0	0	0	$q_1$
2	$\pi/2$	0	$q_2$	0
3	0	0	$q_3$	0
4	0	$L$	0	$q_4$