

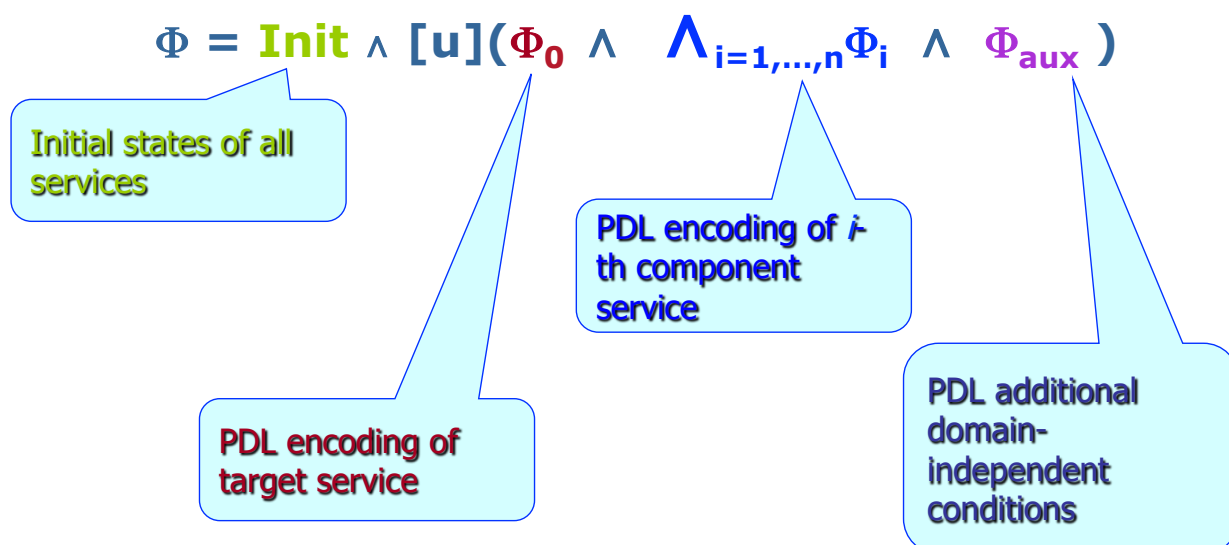
Composition: the “Roman” Approach Reduction to SAT in PDL

Encoding in PDL

Basic idea:

- A orchestrator program P realizes the target service T iff at each point:
 - \forall transition labeled a of the target service T ...
 - ... \exists an available service B_i (the one chosen by P) that can make an a -transition, realizing the a -transition of T
- Encoding in PDL:
 - \forall transition labeled a ...
use **branching**
 - \exists an available service B_i that can make an a -transition ...
use underspecified predicates **assigned through SAT**

Structure of the PDL Encoding



PDL encoding is polynomial in the size of the service TSS

PDL Encoding

- Target service $S_0 = (\Sigma, S_0, s_0^0, \delta_0, F_0)$ in PDL we define Φ_0 as the conjunction of:
 - $s \rightarrow \neg s'$ for all pairs of distinct states in S_0
service states are pair-wise disjoint
 - $s \rightarrow \langle a \rangle T \wedge [a]s'$ for each $s' = \delta_0(s, a)$
target service can do an a -transition going to state s'
 - $s \rightarrow [a] \perp$ for each $\delta_0(s, a)$ undef.
target service cannot do an a -transition
 - $F_0 \equiv \bigvee_{s \in F_0} S$
denotes target service final states
- ...

PDL Encoding (cont.d)

- available services $S_i = (\Sigma, S_i, s_i^0, \delta_i, F_i)$ in PDL we define Φ_i as the conjunction of:
 - $s \rightarrow \neg s'$ for all pairs of distinct states in S_i
Service states are pair-wise disjoint
 - $s \rightarrow [a](\text{moved}_i \wedge s' \vee \neg \text{moved}_i \wedge s)$ for each $s' = \delta_i(s, a)$
if service moved then new state, otherwise old state
 - $s \rightarrow [a](\neg \text{moved}_i \wedge s)$ for each $\delta_i(s, a)$ undef.
if service cannot do a, and a is performed then it did not move
 - $F_i \equiv \bigvee_{s \in F_i} S$
denotes available service final states
- ...

PDL Encoding (cont.d)

- Additional assertions Φ_{aux}
 - $\langle a \rangle T \rightarrow [a] \bigvee_{i=1, \dots, n} \text{moved}_i$ for each action a
at least one of the available services must move at each step
 - $F_0 \rightarrow \bigwedge_{i=1, \dots, n} F_i$
when target service is final all comm. services are final
 - $\text{Init} \equiv s_0^0 \wedge \bigwedge_{i=1, \dots, n} s_i^0$
Initially all services are in their initial state

PDL encoding: $\Phi = \text{Init} \wedge [u](\Phi_0 \wedge \bigwedge_{i=1, \dots, n} \Phi_i \wedge \Phi_{aux})$

Results

Thm[ICSOC' 03,IJCIS' 05]:

Composition exists iff PDL formula Φ SAT

From composition labeling of the target service one can build a tree model of the PDL formula and viceversa

Information on the labeling is encoded in predicates moved,

Corollary [ICSOC' 03,IJCIS' 05]:

Checking composition existence is decidable in **EXPTIME**

Thm[Muscholl&Walukiewicz FoSSaCS'07]:

Checking composition existence is **EXPTIME-hard**

Results on TS Composition

Thm[ICSOC' 03,IJCIS' 05]:

If composition exists then finite TS composition exists.

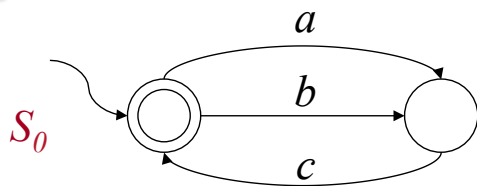
*From a small model of the PDL formula Φ ,
one can build a finite TS machine*

*Information on the output function of the machine is encoded in
predicates moved,*

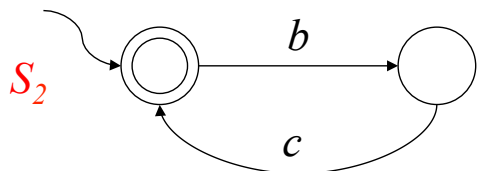
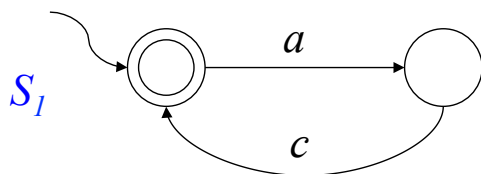
⇒ finite TS composition existence of services expressible as
finite TS is EXPTIME-complete

Example (1)

Target service



Available services



PDL

...
 ...
 ...

$$s_0^0 \wedge s_1^0 \wedge s_2^0$$

$$\langle a \rangle T \rightarrow [a] (\text{moved}_1 \vee \text{moved}_2)$$

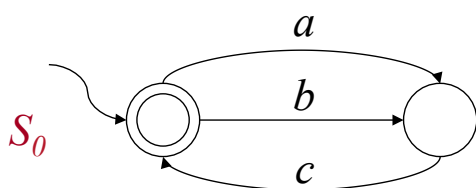
$$\langle b \rangle T \rightarrow [b] (\text{moved}_1 \vee \text{moved}_2)$$

$$\langle c \rangle T \rightarrow [c] (\text{moved}_1 \vee \text{moved}_2)$$

$$F_0 \rightarrow F_1 \wedge F_2$$

Example (2)

Target service



$$s_0^0 \rightarrow \neg s_0^1$$

$$s_0^0 \rightarrow \langle a \rangle T \wedge [a] s_0^1$$

$$s_0^0 \rightarrow \langle b \rangle T \wedge [b] s_0^1$$

$$s_0^1 \rightarrow \langle c \rangle T \wedge [c] s_0^0$$

$$s_0^0 \rightarrow [c] \perp$$

$$s_0^1 \rightarrow [a] \perp$$

$$s_0^1 \rightarrow [b] \perp$$

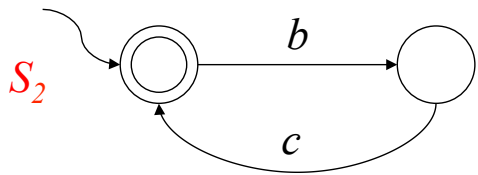
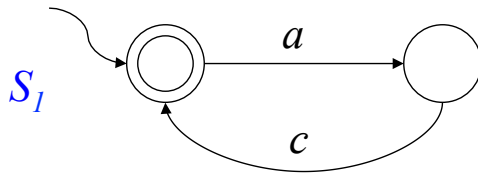
$$F_0 \equiv s_0^0$$

...
 ...
 ...



Example (3)

Available services



...

$$s_1^0 \rightarrow \neg s_1^1$$

$$s_1^0 \rightarrow [a] (\text{moved}_1 \wedge s_1^1 \vee \neg \text{moved}_1 \wedge s_1^0)$$

$$s_1^0 \rightarrow [c] \neg \text{moved}_1 \wedge s_1^0$$

$$s_1^0 \rightarrow [b] \neg \text{moved}_1 \wedge s_1^0$$

$$s_1^1 \rightarrow [a] \neg \text{moved}_1 \wedge s_1^1$$

$$s_1^1 \rightarrow [b] \neg \text{moved}_1 \wedge s_1^1$$

$$s_1^1 \rightarrow [c] (\text{moved}_1 \wedge s_1^0 \vee \neg \text{moved}_1 \wedge s_1^1)$$

$$F_1 \equiv s_1^0$$

$$s_2^0 \rightarrow \neg s_2^1$$

$$s_2^0 \rightarrow [b] (\text{moved}_2 \wedge s_2^1 \vee \neg \text{moved}_2 \wedge s_2^0)$$

$$s_2^0 \rightarrow [c] \neg \text{moved}_2 \wedge s_2^0$$

$$s_2^0 \rightarrow [a] \neg \text{moved}_2 \wedge s_2^0$$

$$s_2^1 \rightarrow [b] \neg \text{moved}_2 \wedge s_2^1$$

$$s_2^1 \rightarrow [a] \neg \text{moved}_2 \wedge s_2^1$$

$$s_2^1 \rightarrow [c] (\text{moved}_2 \wedge s_2^0 \vee \neg \text{moved}_2 \wedge s_2^1)$$

$$F_2 \equiv s_2^0$$

...

Example (4)

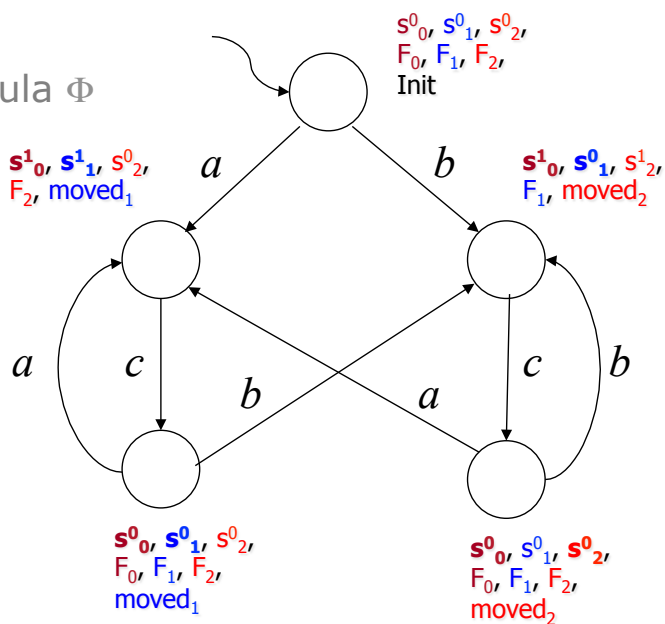


Check: run SAT on PDL formula Φ

Example

Check: run SAT on PDL formula Φ

Yes \Rightarrow (small) model

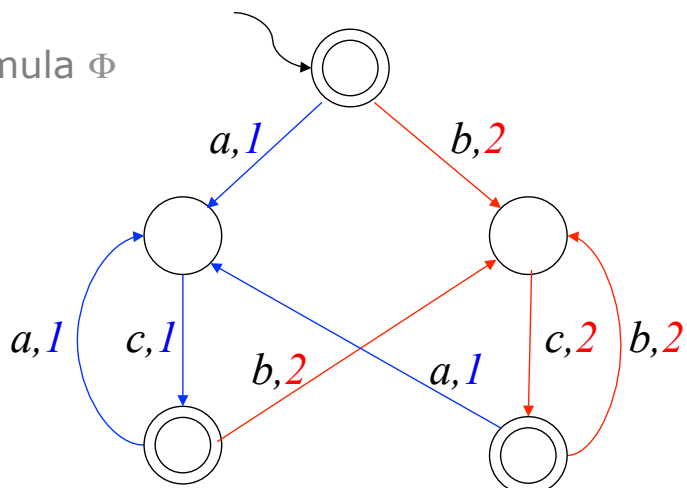


Example

Check: run SAT on PDL formula Φ

Yes \Rightarrow (small) model

\Rightarrow extract finite TS



Example

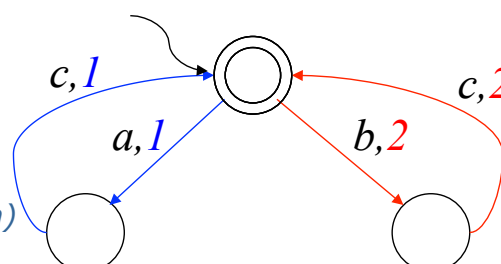
Check: run SAT on PDL formula Φ

Yes \Rightarrow (small) model

\Rightarrow extract finite TS

\Rightarrow minimize finite TS

(similar to Mealy machine minimization)



Results on Synthesizing Composition

- Using PDL reasoning algorithms based on model construction (cf. tableaux), build a (small) model

Exponential in the size of the PDL encoding/services finite TS

Note: SitCalc, etc. can compactly represent finite TS, PDL encoding can preserve compactness of representation

- From this model extract a corresponding finite TS

Polynomial in the size of the model

- Minimize such a finite TS using standard techniques (opt.)

Polynomial in the size of the TS

Note: finite TS extracted from the model is not minimal because encodes output in properties of individuals/states

Tools for Synthesizing Composition

- In fact we use only a fragment of PDL in particular we use fixpoint (transitive closure) only to get the universal modality ...
- ... thanks to a tight correspondence between PDLs and Description Logics (DLs), lately highly optimized tableaux based reasoning systems are available to:
 - check for composition existence
 - do composition synthesis (*if the ability or returning models is present*)
- Among them we recall:
 - Racer (<http://www.racer-systems.com/>) based on DLs
 - Pellet (<http://clarkparsia.com/pellet>) based on DLs
 - Fact++ (<http://owl.man.ac.uk/factplusplus/>) based on DLs
 - PDL Tableaux (<http://www.cs.manchester.ac.uk/~schmidt/pdl-tableau/>) based on PDL
 - Tableaux Workbench (<http://twb.rsise.anu.edu.au/>) based on PDL
 - Lotrec (<http://www.irit.fr/Lotrec/>) based on PDL

Reduction to PDL SAT works also for nondeterministic available services

Technique1: Reduction to PDL

Basic idea:

- A orchestrator program P realizes the target service T iff at each point:
 - \forall transition labeled a of the target service T ...
 - ... \exists an available service B_i (the one chosen by P) which can make an a -transition ...
 - ... and $\forall a$ -transition of B_i realize the a -transition of T
- Encoding in PDL:
 - \forall transition labeled a ...
use **branching**
 - \exists an available service B_i ...
use underspecified predicates **assigned through SAT**
 - $\forall a$ -transition of B_i ... :
use **branching** again

Technical Results: Practical

Reduction to PDL provides also a practical sound and complete technique to compute the orchestrator program also in this case

eg, PELLET @ Univ. Maryland

- Use state-of-the-art tableaux systems for OWL-DL for checking SAT of PDL formula Φ coding the composition existence
- If SAT, the tableau returns a finite model of Φ
exponential in the size of the behaviors
- Project away irrelevant predicates from such model, and possibly minimize
- The resulting structure is a finite orchestrator program that realizes the target behavior
polynomial in the size of the model